

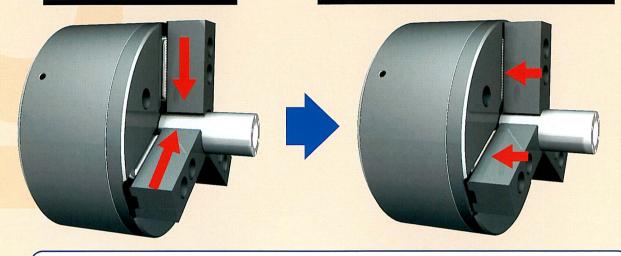


# Jaw parallel shift drawing-down chuck

- ©The work seating can be checked and the stable accuracy is acquired by drawing-down.
- This chuck can respond from various kind of small quantity to mass-production processing.
- The chuck realizes cost effectiveness, because the conventional standard jaws (Serration jaws) can be used.

### Jawe parallel shift

### Drawing-down after chucking



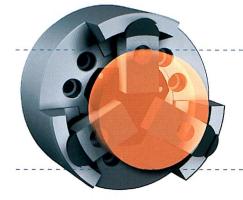
# Merit 1 Wide chucking range.



In case of a general drawing-down chuck gripping range is narrow.



In case of DL chuck, gripping range is wide.

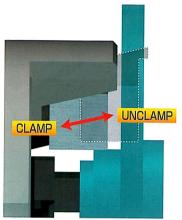




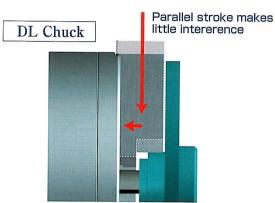
When gripping range is small even the same diameter of works, chuck size can be reduced.



## Merit 2 The chuck does not interfere with Z-axis.



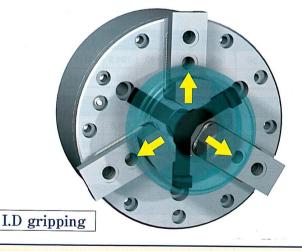
In case of a general chuck, because jaws protrude in Z-axis direction, Z-axis interferes with work. Also, the chuck is difficult to grip the narrow portion of a work.



In case of DL chuck, since jaws do not protrude in Z-axis direction, Z-axis does not interfere with work and the loader can approach chuck. As a result, the chuck can grip the narrow portion of a work.

# Merit 3 A chuck enables gripping Note) When changing I.D gripping and 0.D gripping, it is necessary to remove the front cover and turn master jaws 180°.





### Merit 4

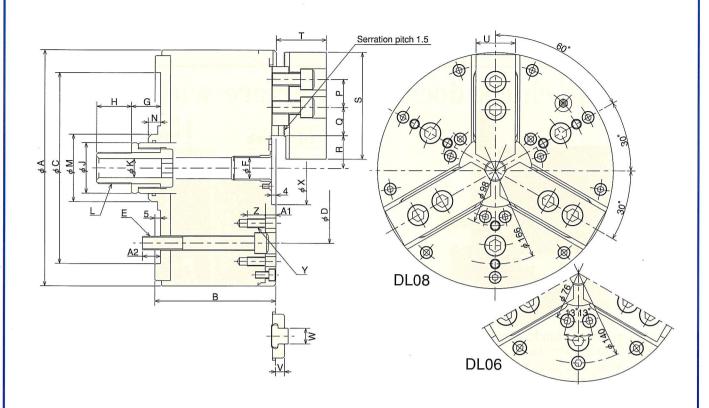
# Dust-proof · grease-enclosed structure.

It can be used for an automation line, and also, work seating can be checked. Since the chuck has high durability due to dust-proof • grease-enclosed structure.

#### Serration jaws used. Merit 5

It is easy to change jaws and it makes cost effectiveness to customers because the serration jaws are applied to the chuck. It is also the best for limited production of diversified products, because a customer can machine and form the soft jaws by itself.





=	Model	Α	В	С	D	B	F	G (max.)	G (min.)	Н	J	К	L	М	N	Р
	DL06	169	88	140		3-M10	19	33.5	23	31	42	17	M26×1.5	55	8.5	20
	DL08	210	108	170	133.4	3-M12	19	39.5	26	31	45	17	M28×1.5	60	11	25
		0	0	D	D				Royal South							
=	Model	Q (max.)	Q (min.)	R (max.)	R (min.)	S	T	U	V	W	Х	Υ		Z	A1	A2
Ξ	DL06	21.25	13.75	23.6	20.8	72	38.5	31	7.3	12	51	3×5	-М6	12	9.5	16

Ξ	State Control of the													
	Model	Gripping I			Plunger Stroke	Max.Draw Bar Pull Force	Max.Gripping Force	Max.Speed	Net Weight with Soft top jaws	Moment of inertia	Matching	Max.pressure	Min.pressure	Matching Soft
		Max.	Min.	diameter (mm)	(mm)	kN (kgf)	kN (kgf)	(min <sup>-1</sup> )	(kg)	(kg·m²)	Cylinder	MPa (kgf/cm²)	MPa (kgf/cm²)	top jäw
	DL06	169	20	5.6	10.5	22 (2243)	57 (5812)	6000	16	0.045	Y1020R	3.1 (31)	(8) 8.0	SB06B1
Ξ	DL08	210	20	7.2	13.5	31 (3161)	84 (8566)	5000	30	0.135	Y1225R	3.0 (30)	0.8(8)	SB08B1

3×2-M8

\*\*Specifications and appearance may be changed without a prior notice for improvement.

25.3

DL08

25.25 16.25

### **KITAGAWA**

KITAGAWA IRON WORKS CO.,LTD.

77-1 Motomachi, Fuchu-shi, Hiroshima-pref., 726-8610 Japan

Kitagawa Home Page

http://www.kiw.co.jp/